

LIBRARY BINDING

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Outline

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- Modeling and problem analysis.
- Rule-based systems for library binding.
- Algorithms for library binding:
 - *Structural covering/matching.*
 - *Boolean covering/matching.*
- Concurrent optimization and binding.

Library binding

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- Given an unbound logic network and a set of library cells:
 - Transform into an interconnection of instances of library cells.
 - Optimize *area*, (under *delay* constraints.)
 - Optimize *delay*, (under *area* constraints.)
 - Optimize *power*, (under *delay* constraints.)
- Called also *technology mapping*:
 - Method used for re-designing circuits in different technologies.

Library models

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- Combinational elements:
 - Single-output functions:
 - * e.g. AND, OR, AOI.
 - Compound cells: e.g. adders, encoders.
- Sequential elements:
 - Registers, counters.
- Miscellaneous:
 - Schmitt triggers.

Major approaches

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- Rule-based systems:
 - Mimic designer activity.
 - Handle all types of cells.
- Heuristic algorithms:
 - Restricted to single-output combinational cells.
- Most tools use a combination of both.

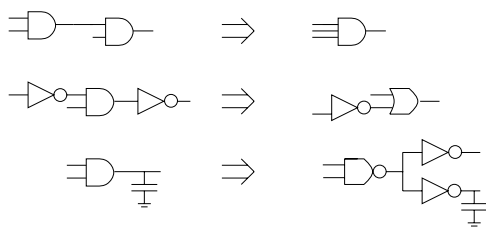
Rule-based library binding

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- Binding by stepwise transformations.
- Data-base:
 - Set of patterns associated with best implementation.
- Rules:
 - Select subnetwork to be mapped.
 - Handle high-fanout problems, buffering, etc.

Example

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Strategies

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- Search for a sequence of transformations.
- Search space:
 - *Breadth* (options at each step).
 - *Depth* (look-ahead).
- *Meta-rules* determine dynamically breadth and depth.

Rule-based library binding

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- Advantages:
 - Applicable to all kinds of libraries.
- Disadvantages:
 - Large rule data-base:
 - * Completeness issue.
 - * Formal properties of bound network.
 - Data-base updates.

Algorithms for library binding

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- Mainly for single-output combinational cells.
- Fast and efficient:
 - Quality comparable to rule-based systems.
- Library description/update is simple:
 - Each cell modeled by its function or equivalent pattern.

Problem analysis

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- Matching:
 - A cell matches a sub-network if their terminal behavior is the same.
 - Input-variable *assignment* problem.
- Covering:
 - A cover of an unbound network is a partition into subnetworks which can be replaced by library cells.

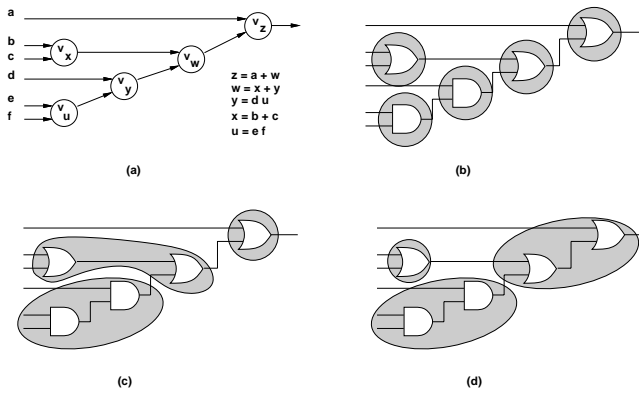
Assumptions

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- Network granularity is fine.
 - Decomposition into *base* functions.
 - * 2-input *AND, OR, NAND, NOR*.
- Trivial binding:
 - Replacement of each vertex by base cell.

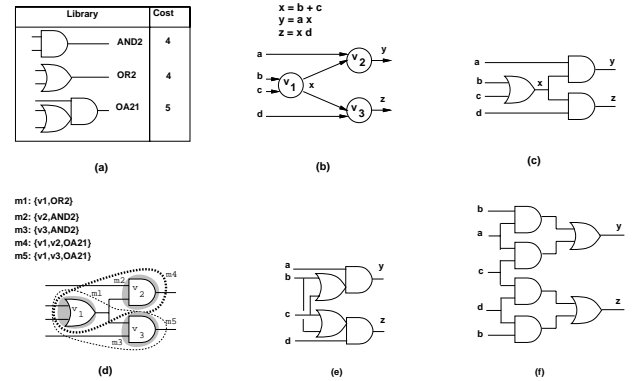
Example

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Example

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Example

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- Vertex covering:
 - Covering v_1 : $(m_1 + m_4 + m_5)$.
 - Covering v_2 : $(m_2 + m_4)$.
 - Covering v_3 : $(m_3 + m_5)$.
- Input compatibility:
 - Match m_2 requires m_1 :
* $(m'_2 + m_1)$.
 - Match m_3 requires m_1 :
* $(m'_3 + m_1)$.
- Overall *binate* clause:
 - $(m_1 + m_4 + m_5)(m_2 + m_4)(m_3 + m_5)(m'_2 + m_1)(m'_3 + m_1) = 1$

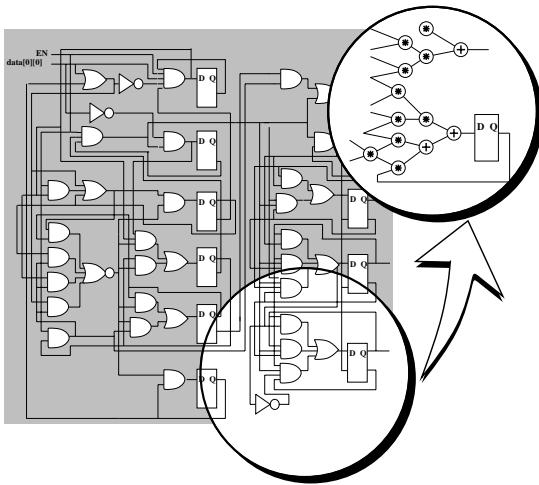
Heuristic algorithms

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- Decomposition:
 - Cast network and library in standard form.
 - Decompose into *base functions*.
 - Example: NAND2 and INV.
- Partitioning:
 - Break network into *cones*.
 - Reduce to many multi-input single-output subnetworks.
- Covering:
 - Cover each subnetwork by library cells.

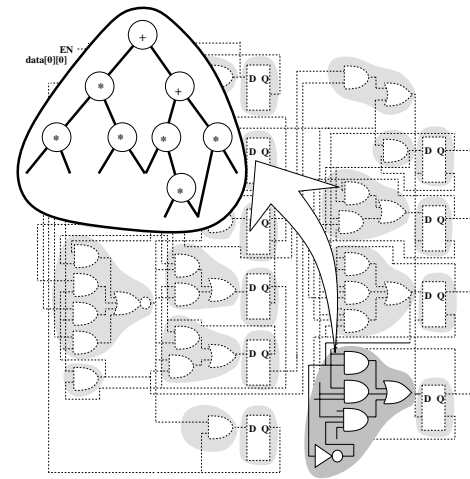
Decomposition

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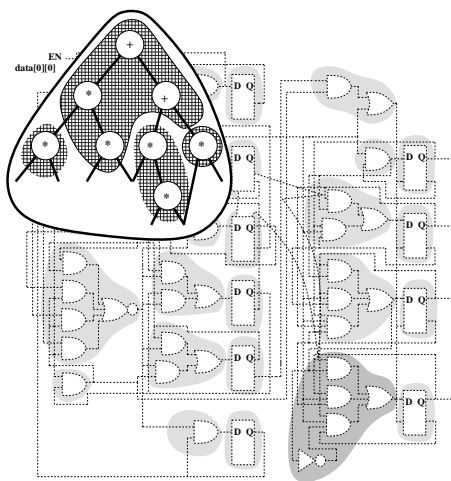
Partitioning

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Covering

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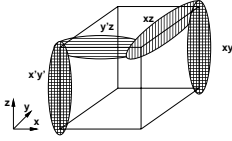
Heuristic algorithms

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- Structural approach:
 - Model functions by *patterns*.
 - * Example: trees, dags.
 - Rely on *pattern matching* techniques.
- Boolean approach:
 - Use Boolean models.
 - Solve *tautology* problem.
 - More powerful.

Example Boolean versus structural matching

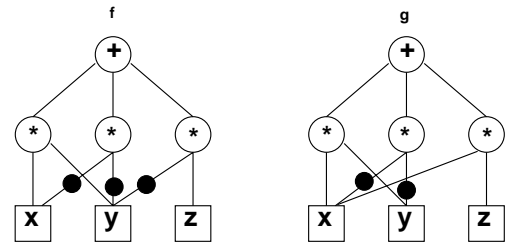
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- $f = xy + x'y' + y'z$
- $g = xy + x'y' + xz$
- Function equality is a tautology:
 - Boolean match.
- Patterns may be different:
 - Structural match may not be found.

Example Boolean versus structural matching

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- $f = xy + x'y' + y'z$
- $g = xy + x'y' + xz$
- Patterns do not match.

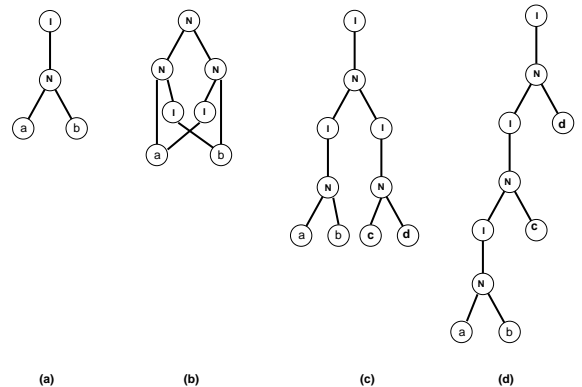
Structural matching and covering

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- Expression patterns:
 - Represented by dags.
- Identify pattern dags in network:
 - Sub-graph isomorphism.
- Simplification:
 - Use tree patterns.

Example

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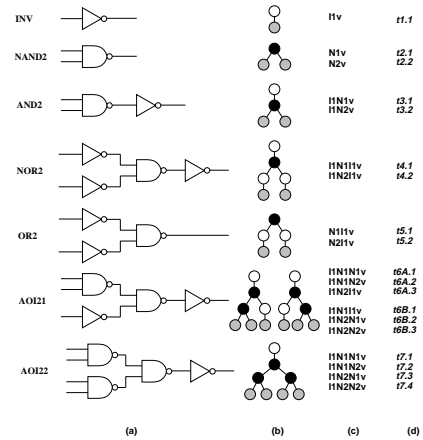
Tree-based matching

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- Network:
 - Partitioned and decomposed:
 - * NOR2 (or NAND2) + INV.
 - * Generic base functions.
 - *Subject tree*.
- Library:
 - Represented by trees.
 - Possibly more than one tree per cell.
- Pattern recognition:
 - Simple binary tree match.
 - Aho-Corasick automaton.

Simple library

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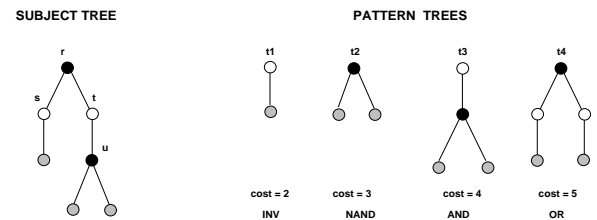
Tree covering

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- Dynamic programming:
 - Visit subject tree bottom-up.
- At each vertex:
 - Attempt to match:
 - * Locally rooted subtree.
 - * All library cells.
- *Optimum* solution, for the subtree.

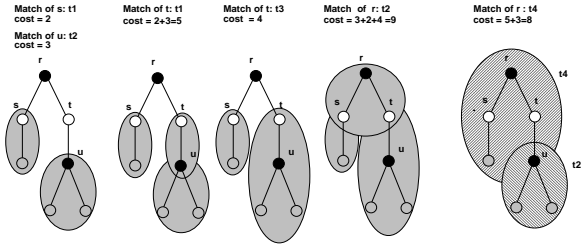
Example

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Example

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Example

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- Minimum-area cover.
- Area costs:
 - INV:2; NAND2:3; AND2:4; AOI21:6.
- Best choice:
 - AOI21 fed by a NAND2 gate.

Example

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Network	Subject graph	Vertex	Match	Gate	Cost
		x	t2	NAND2(b,c)	3
		y	t1	INV(a)	2
		z	t2	NAND2(x,d)	$2 \cdot 3 = 6$
		w	t2	NAND2(y,z)	$3 \cdot 3 + 2 = 11$
		o	t1	INV(w)	$3 \cdot 3 + 2 \cdot 2 = 13$
			t3	AND2(y,z)	$2 \cdot 3 + 4 + 2 = 12$
	t6B	AOI21(x,d,a)	$3 + 6 = 9$		

Minimum delay cover

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- Dynamic programming approach.
- Cost related to gate delay.
- Delay modeling:
 - Constant gate delay.
 - * Straightforward.
 - Load-dependent delay:
 - * Load fanout unknown.
 - * Binning techniques.

Minimum delay cover constant delays

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- The cell pattern tree and the rooted subtree are isomorphic.
 - The vertex is labeled with the cell delay.
- The cell tree is isomorphic to a subtree with leaves L .
 - The vertex is labeled with the cell cost plus the *maximum* of the labels of L .

Example

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- Inputs data-ready times are 0 except for $t_d = 6$.
- Constant delays:
 - INV:2; NAND2:4; AND2:5; AOI21:10.
- Compute *data-ready* times bottom-up:
 - $t_x = 4, t_y = 2; t_z = 10, t_w = 14$.
- Best choice:
 - AND2, two NAND2 and an INV gate.

Example

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Network	Subject graph	Vertex	Match	Gate	Cost
		x	t_2	NAND2(b,c)	4
		y	t_1	INV(a)	2
		z	t_2	NAND2(x,d)	$6 + 4 = 10$
		w	t_2	NAND2(y,z)	$10 + 4 = 14$
		o	t_1	INV(w)	$14 + 2 = 16$
			t_3	AND2(y,z)	$10 + 5 = 15$
			t_{6B}	AOI21(x,d,a)	$10 + 6 = 16$

Minimum delay cover load-dependent delays

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- Model:
 - Assume a finite set of load values.
- Dynamic programming approach:
 - Compute an array of solutions for each possible load.
 - For each input to a matching cell the best match for any load is selected.
- *Optimum* solution, when all possible loads are considered.

Example

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- Inputs data-ready times are 0 except for $t_d = 6$.
- Load-dependent delays:
 - INV:1+l; NAND2:3+l; AND2:4+l; AOI21:9+l.
- Loads:
 - INV:1; NAND2:1; AND2:1; AOI21:1.
- Same solution as before.

Example

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- Inputs data-ready times are 0 except for $t_d = 6$.
- Load-dependent delays:
 - INV:1+l; NAND2:3+l; AND2:4+l; AOI21:9+l; SINV:1+0.5l.
- Loads:
 - INV:1; NAND2:1; AND2:1; AOI21:1; SINV:2.
- Assume output load is 1:
 - Same solution as before.
- Assume output load is 5:
 - Solution uses SINV cell.

Example

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Network	Subject graph	Vertex	Match	Gate	Cost		
					Load=1	Load=2	Load=5
		x	t2	NAND2(b,c)	4	5	8
		y	t1	INV(a)	2	3	6
		z	t2	NAND2(x,d)	10	11	14
		w	t2	NAND2(y,z)	14	15	18
		o	t1	INV(w)			20
			t3	AND2(y,z)			19
			t6B	AOI21(x,d,a)			20
				SINV(w)			18.5

Library binding and polarity assignment

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- Search for lower cost solution by not constraining the signal polarities.
- Most circuit allow us to choose the input/output signal polarities.
- Approaches:
 - Structural covering.
 - Boolean covering.

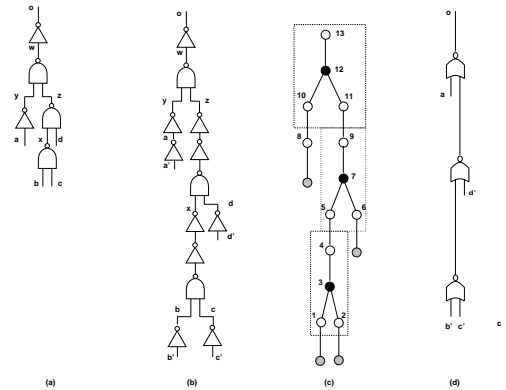
Structural covering and polarity assignment

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- Pre-process subject network:
 - Add inverter pairs between NANDs.
 - Provide signals with both polarity.
- Add inverter-pair cell to the library:
 - To eliminate unneeded pairs.
 - Cell corresponds to a connection with zero cost.

Example

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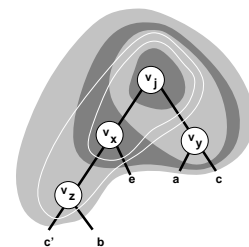
Boolean covering

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- Decompose network into base functions.
- When considering vertex v_i :
 - Construct *clusters* by local elimination.
 - Several functions associated with v_i .
- Limit size and depth of clusters.

Example

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$$\begin{aligned}
 f_{j,1} &= xy; \\
 f_{j,2} &= x(a+c); \\
 f_{j,3} &= (e+z)y; \\
 f_{j,4} &= (e+z)(a+c); \\
 f_{j,5} &= (e+c'+d)y; \\
 f_{j,6} &= (e+c'+d)(a+c);
 \end{aligned}$$

Boolean matching

\mathcal{P} -equivalence

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- *Cluster function* $f(\mathbf{x})$: sub-network behavior.
- *Pattern function* $g(\mathbf{y})$: cell behavior.
- \mathcal{P} -equivalence:
 - Exists a permutation operator \mathcal{P} , such that $f(\mathbf{x}) = g(\mathcal{P} \mathbf{x})$ is a tautology?
- Approaches:
 - Tautology check over all input permutations.
 - Multi-rooted pattern ROBDD capturing all permutations.

Input/output polarity assignment

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- Allow for reassignment of input/output polarity.
- \mathcal{NPN} classification of Boolean functions.
- \mathcal{NPN} -equivalence:
 - Exists a permutation matrix \mathcal{P} , and complementation operators $\mathcal{N}_i, \mathcal{N}_o$ such that $f(\mathbf{x}) = \mathcal{N}_o g(\mathcal{P} \mathcal{N}_i \mathbf{x})$ is a tautology?
- Variations:
 - \mathcal{N} -equivalence, \mathcal{PN} -equivalence

Boolean matching

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- *Pin assignment* problem.
 - Map cluster variables \mathbf{x} to pattern vars \mathbf{y} .
 - Characteristic equation: $\mathcal{A}(\mathbf{x}, \mathbf{y}) = 1$.
- Pattern function under variable assignment:
 - $g_{\mathcal{A}}(\mathbf{x}) = \mathcal{S}_{\mathbf{y}} \mathcal{A}(\mathbf{x}, \mathbf{y}) g(\mathbf{y})$
- *Tautology problem*.
 - $f(\mathbf{x}) \bar{\oplus} g_{\mathcal{A}}(\mathbf{x})$
 - $\forall \mathbf{x} (f(\mathbf{x}) \bar{\oplus} \mathcal{S}_{\mathbf{y}} (\mathcal{A}(\mathbf{x}, \mathbf{y}) g(\mathbf{y})))$

Example

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- Assign x_1 to y'_2 and x_2 to y_1 .
- Characteristic equation:
 - $\mathcal{A}(x_1, x_2, y_1, y_2) = (x_1 \oplus y_2)(x_2 \bar{\oplus} y_1)$
- AND pattern function:
 - $g = y_1 y_2$
- Pattern function under assignment:
 - $\mathcal{S}_{y_1, y_2} \mathcal{A} g =$
 $= \mathcal{S}_{y_1, y_2} (x_1 \oplus y_2)(x_2 \bar{\oplus} y_1) y_1 y_2 = x_2 x'_1$

Signatures and filters

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- Capture some properties of Boolean functions.
- If signatures do not match, there is no match.
- Used as filters to reduce computation.
- Signatures:
 - Unateness.
 - Symmetries.
 - Co-factor sizes.
 - Spectra.

Filters based on unateness and symmetries

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- Any pin assignment must associate
 - unate (binate) variables in $f(\mathbf{x})$ with unate (binate) variables in $g(\mathbf{y})$.
- Variables or groups of variables
 - that are interchangeable in $f(\mathbf{x})$ must be interchangeable in $g(\mathbf{y})$.

Example

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- Cluster function: $f = abc$.
 - Symmetries: $\{(a, b, c)\}$ – unate.
- Pattern functions:
 - $g_1 = a + b + c$
 - * Symmetries: $\{(a, b, c)\}$ – unate.
 - $g_2 = ab + c$
 - * Symmetries: $\{(a, b)(c)\}$ – unate.
 - $g_3 = abc' + a'b'c$
 - * Symmetries: $\{(a, b, c)\}$ – binate.

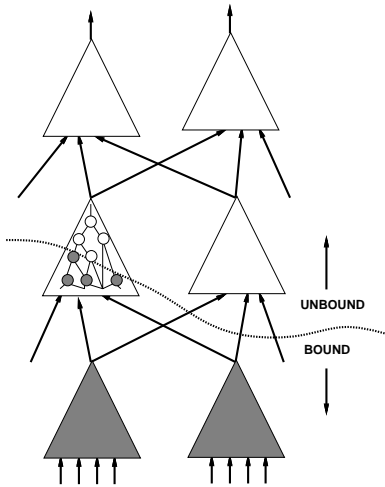
Concurrent optimization and library binding

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- Motivation:
 - Logic simplification is usually done prior to binding.
 - Logic simplification/substitution can be combined with binding.
- Mechanism:
 - Binding induces some *don't care* conditions.
 - Exploit *don't cares* as degrees of freedom in matching.

Example

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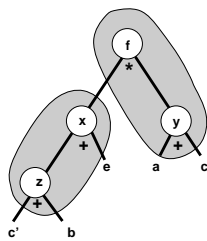
Boolean matching with *don't care* conditions

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- Given $f(\mathbf{x})$, $f_{DC}(\mathbf{x})$ and $g(\mathbf{y})$:
 - g matches f if g is equivalent to \tilde{f} where $f \cdot f'_{DC} \leq \tilde{f} \leq f + f_{DC}$
- Matching condition:
 - $\forall \mathbf{x}(f_{DC}(\mathbf{x}) + f(\mathbf{x}) \oplus \mathcal{S}_{\mathbf{y}}(\mathcal{A}(\mathbf{x}, \mathbf{y}) g(\mathbf{y})))$

Example

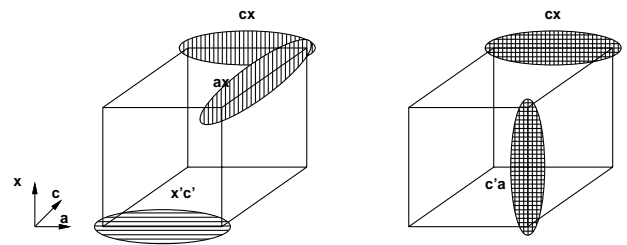
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- Assume v_x is bound to $OR3(c', b, e)$.
- Don't care* set includes $x \oplus (c' + b + e)$.
- Consider $f_j = x(a + c)$ with $CDC = x'c'$.
- No simplification. Mapping into *AOI* gate.
- Matching with DC. Mapping into *MUX* gate.

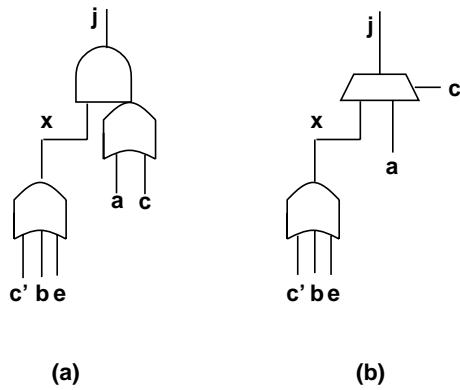
Example

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Example

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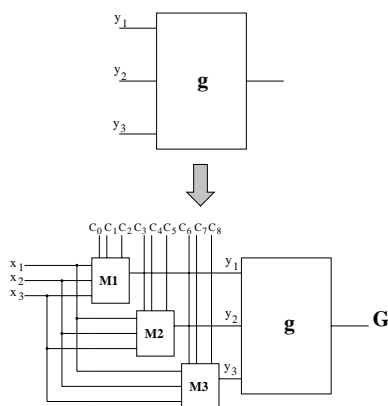
Extended matching

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- Augment pattern function with mux function.
 - Each cell input can be routed to any cluster input (or voltage rail).
 - Input polarity can be changed.
 - Cell and cluster may differ input size.
- Define composite function $G(\mathbf{x}, \mathbf{c})$:
 - Pin assignment is determining \mathbf{c} .
- Matching formula: $M(\mathbf{c}) = \forall \mathbf{x} [G(\mathbf{x}, \mathbf{c}) \oplus f(\mathbf{x})]$

Example

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- $g = y_1 + y_2 y_3'$
- $y_1(\mathbf{c}, \mathbf{x}) = (c_0 c_1 x_1 + c_0' c_1' x_2 + c_0' c_1 x_3) \oplus c_2$
- $G = y_1(\mathbf{c}, \mathbf{x}) + y_2(\mathbf{c}, \mathbf{x}) y_3(\mathbf{c}, \mathbf{x})'$

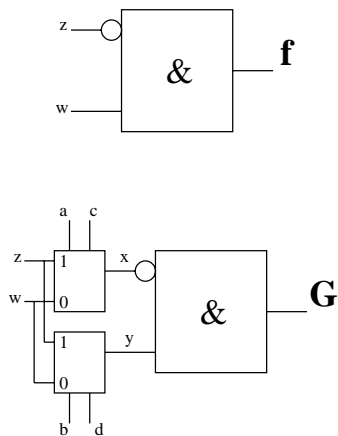
Extended matching modeling

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- Model composite functions by ROBDDs.
 - Assume: n -input cluster and m -input cell.
 - For each cell input:
 - * $\lceil \log_2 n \rceil$ variables for pin permutation.
 - * One variable for input polarity.
 - Total size of \mathbf{c} : $m(\lceil \log_2 n \rceil + 1)$.
- A match exists if there is at least one value of \mathbf{c} satisfying $M(\mathbf{c}) = \forall \mathbf{x} [G(\mathbf{x}, \mathbf{c}) \oplus f(\mathbf{x})]$.

Example

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- $g = x'y, f = wz'$
- $G(a, b, c, d, w, z) = (c \oplus (za + wa'))'(d \oplus (zb + wb'))$
- $f \oplus G = (wz') \oplus ((c \oplus (za + wa'))'(d \oplus (zb + wb')))$
- $M(a, b, c, d) = ab'c'd' + a'bcd$

Extended matching

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- Captures implicitly all possible matches.
- No extra burden when exploiting *don't care* sets.
 - $M(\mathbf{c}) = \forall_{\mathbf{x}} [G(\mathbf{x}, \mathbf{c}) \oplus f(\mathbf{x}) + f_{DC}(\mathbf{x})]$
- Efficient BDD-based representation.
- Extensions to support multiple-output matching

Summary

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- Library binding is very important.
- Rule-based approach:
 - General, sometimes inefficient.
- Algorithmic approach:
 - Pattern-based: fast, but limited.
 - Boolean: more general and efficient.