

# LOGIC SYNTHESIS AND TWO-LEVEL LOGIC OPTIMIZATION

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# Outline

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- Overview of logic synthesis.
- Combinational-logic design:
  - Background.
  - Two-level forms.
- Exact minimization.
- Covering algorithms.
- Boolean relations.

# Logic synthesis and optimization

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- Determine microscopic structure of the circuit.
- Explore (*area-delay*)trade-off:
  - Combinational circuits:
    - \* I/O delay.
  - Sequential circuits:
    - \* *cycle-time*.
- Explore (*power-delay*)trade-off:
- Enhance circuit *testability*.

# Circuit implementation issues

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- Implementation styles:
  - Two-level (e.g. PLA macro cells).
  - Multi-level (e.g. cell-based, array-based).
  
- Operation:
  - Combinational.
  - Sequential:
    - \* Synchronous
    - \* Asynchronous.

# Design flow in logic synthesis

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- Circuit capture:
  - Tabular specifications of functions or *finite-state machines* (FSMs).
  - Schematic capture.
  - Hardware Description Languages (HDLs).
- Synthesis and optimization:
  - Map circuit representation to abstract model.
  - Transformations on abstract model.
  - Library binding.

## Abstract models

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- Models based on graphs.
- Useful for:
  - Machine-level processing.
  - Reasoning about properties.
- Derived from language models by compilation.

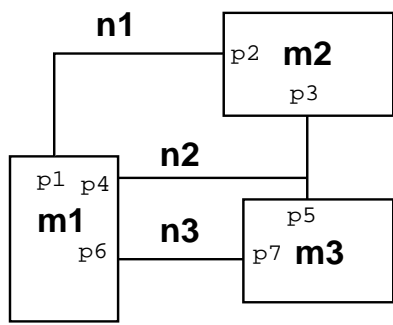
## Structural views

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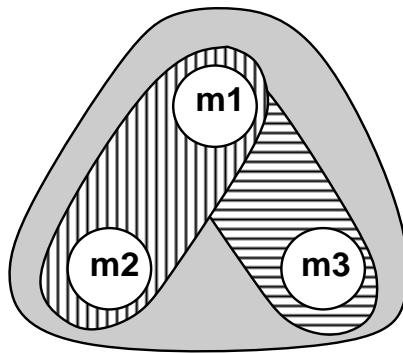
- Netlists:
  - Modules, nets, incidence.
  - Ports.
  - Hierarchy.
- Incidence (sparse) matrix of a graph.

# Example

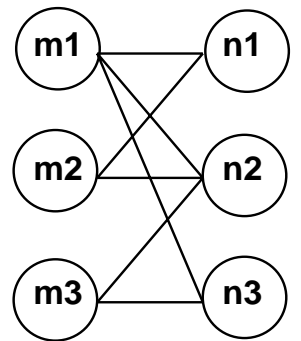
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(a)



(b)



(c)



## Logic functions

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- Black-box model of a combinational module.
- Defined on Boolean Algebra.
- *Support variables* correspond to module inputs.
- Logic functions may have multiple outputs and be *incompletely specified*.

## Logic networks

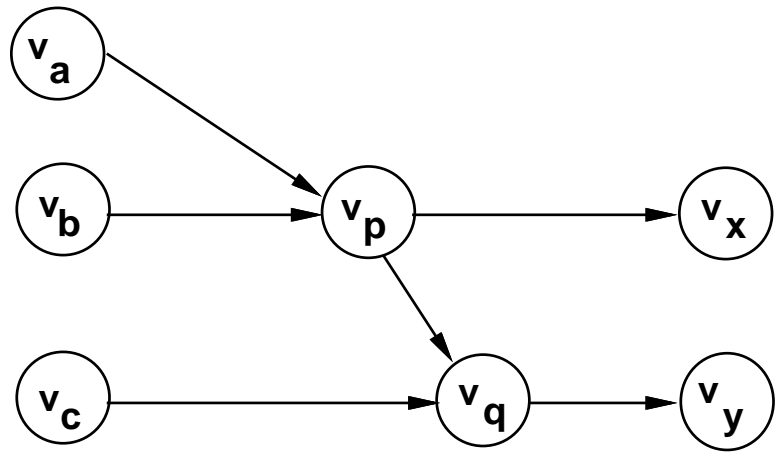
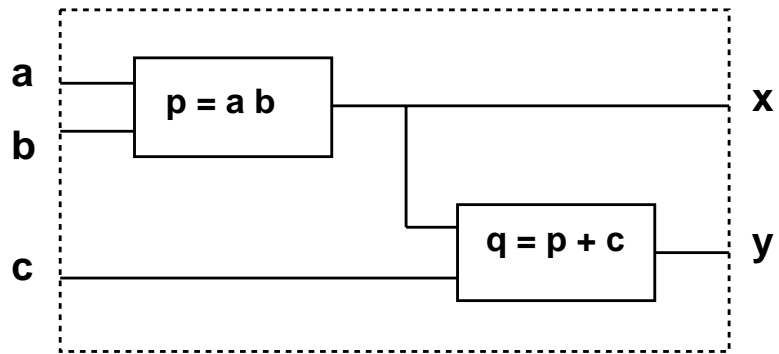
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- Mixed structural/behavioral views.
- Useful for multiple-level logic (combinational and sequential).
- Interconnection of modules:
  - Logic gates.
  - Logic functions.

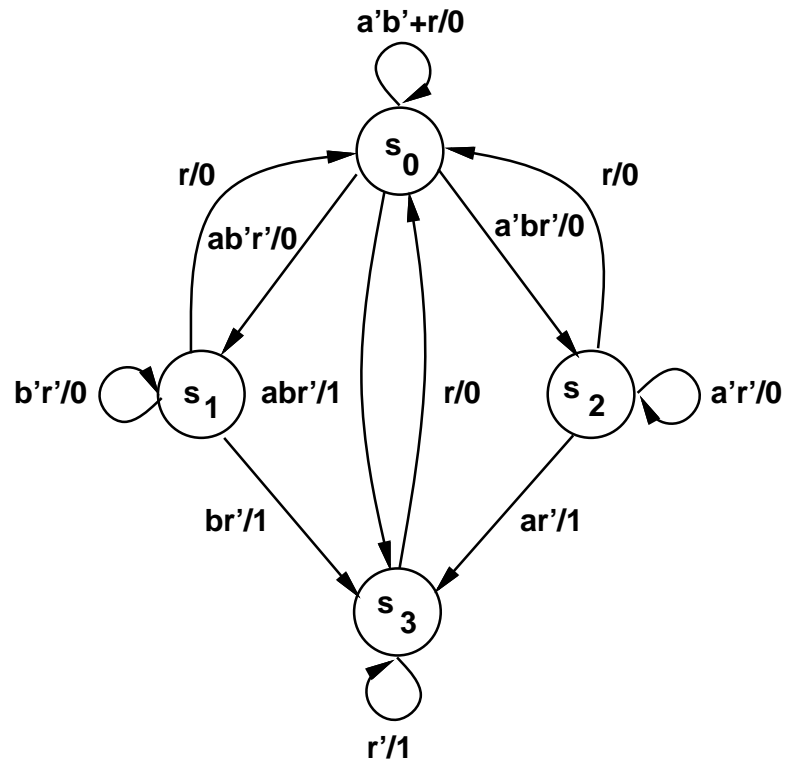
# Example

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# State diagrams

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- Model behavior of sequential circuits.
- Graph:
  - Vertices = states.
  - Edges = transitions.

# Major logic synthesis problems

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- Optimization of logic function representation.
  - Minimization of two-level forms.
  - Optimization of Binary Decision Diagrams (BDDs).
- Synthesis of combinational multiple-level logic networks.
  - Optimization of area, delay, power, testability.
- Optimization of FSM models.
  - State minimization, encoding.
- Synthesis of sequential multiple-level logic networks.
  - Optimization of area, delay, power, testability.
- Library binding.
  - Optimal selection of library cells.

# Combinational logic design background

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- Boolean algebra:
  - Quintuple  $(B, +, \cdot, 0, 1)$
  - Binary Boolean algebra  $B = \{0, 1\}$
- Boolean function:
  - Single output:  $f : B^n \rightarrow B$ .
  - Multiple output:  $f : B^n \rightarrow B^m$ .
  - Incompletely specified:
    - \* *don't care* symbol \*.
    - \*  $f : B^n \rightarrow \{0, 1, *\}^m$ .

## The *don't care* conditions

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- We don't care about the value of the function.
- Related to the environment:
  - Input patterns that never occur.
  - Input patterns such that some output is never observed.
- Very important for synthesis and optimization.

## Definitions

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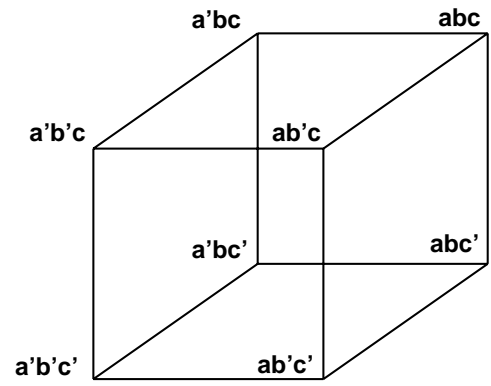
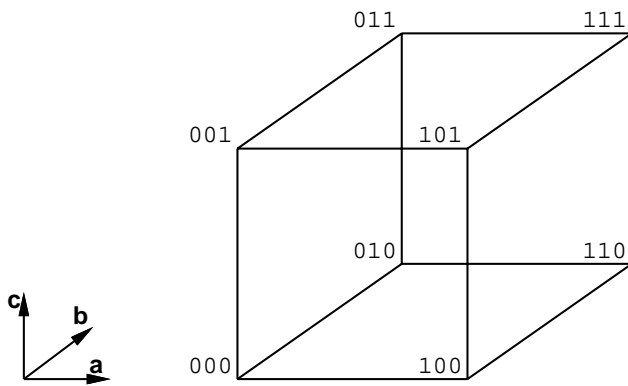
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- Scalar function:
  - *ON – set*: subset of the domain such that  $f$  is true.
  - *OFF – set*: subset of the domain such that  $f$  is false.
  - *DC – set*: subset of the domain such that  $f$  is a *don't care* .
- Multiple-output function:
  - Defined for each component.



# Cubical representation

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# Definitions

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- Boolean *variables*.
- Boolean *literal*: variable and complement.
- *Product* or *cube*: product of literals.
- *Implicant*: product implying a value of a function (usually TRUE).
  - *Hypercube* in the Boolean space.
- *Minterm*: product of all input variables implying a value of a function (usually TRUE).
  - *Vertex* in the Boolean space.

## Tabular representations

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- *Truth table:*
  - List of all minterms of a function.
- *Implicant table or cover:*
  - List of implicants of a function sufficient to define function.
- Remark:
  - Implicant tables are smaller in size.

## Example of truth table

$$x = ab + a'c; \quad y = ab + bc + ac$$

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abc	xy
000	00
001	10
010	00
011	11
100	00
101	01
110	11
111	11

## Example of implicant table

$$x = ab + a'c; \quad y = ab + bc + ac$$

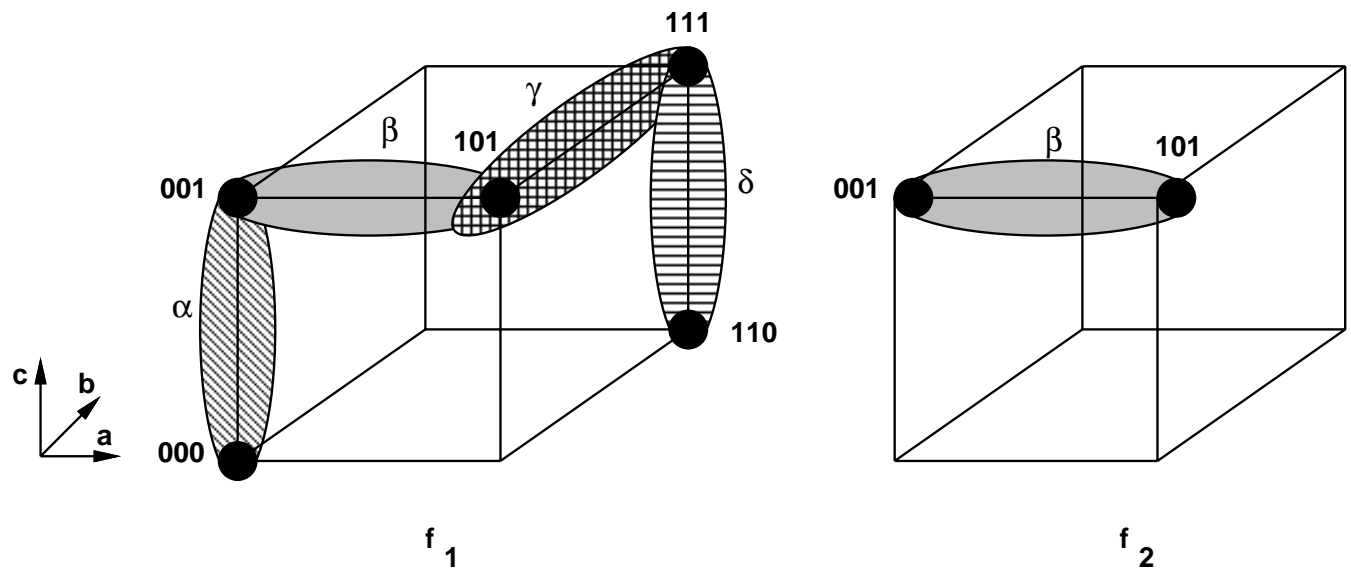
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© GDM

abc	xy
001	10
*11	11
101	01
11*	11

# Cubical representation of minterms and implicants

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- $f_1 = a'b'c' + a'b'c + ab'c + abc + abc'$

- $f_2 = a'b'c + ab'c$

## Two-level logic optimization motivation

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- Reduce size of the representation.
- Direct implementation:
  - PLAs – reduce size and delay.
- Other implementation styles (e.g. multi-level):
  - Reduce amount of information.
  - Simplify local functions and connections.

## Programmable logic arrays

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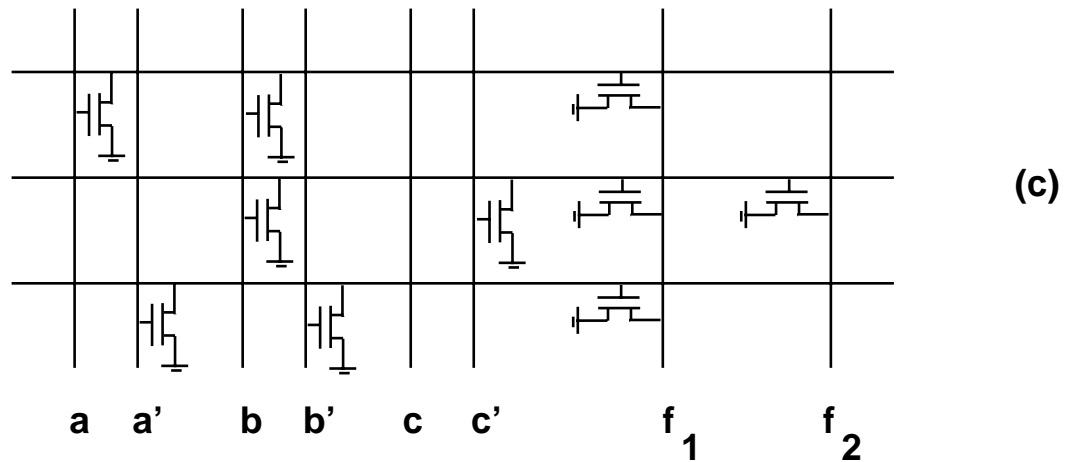
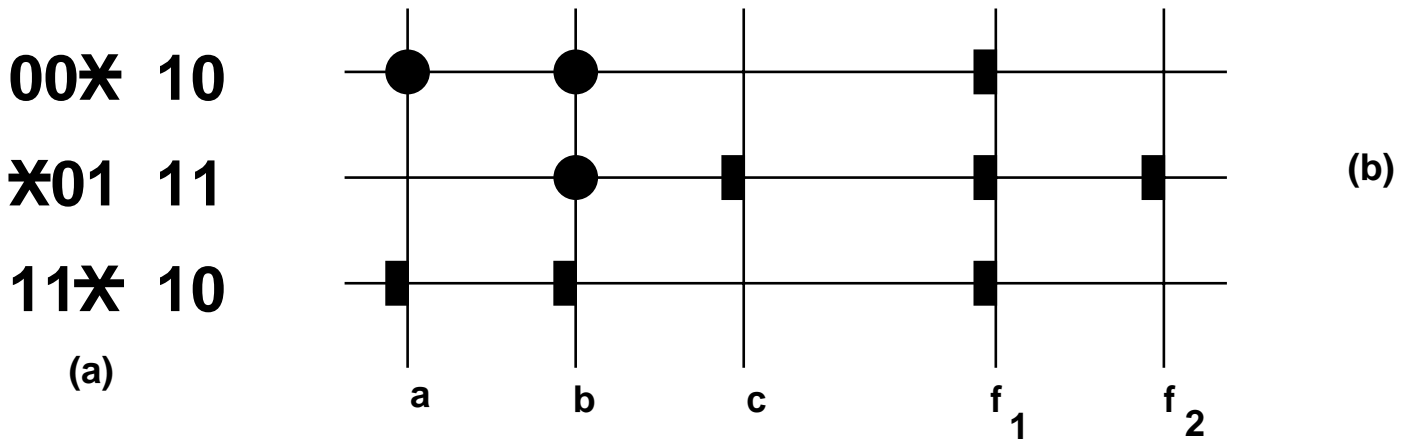
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- Macro-cells with rectangular structure.
- Implement any multi-output function.
- Layout easily generated by module generators.
- Fairly popular in the seventies/eighties (NMOS).
- Still used for control-unit implementation.



# Programmable logic array

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- $f_1 = a'b' + b'c + ab$        $f_2 = b'c$

## Two-level optimization

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- Assumptions:
  - Primary goal is to reduce the number of implicants.
  - All implicants have the same cost.
  - Secondary goal is to reduce the number of literals.
- Rationale:
  - Implicants correspond to PLA rows.
  - Literals correspond to transistors.

## Definitions

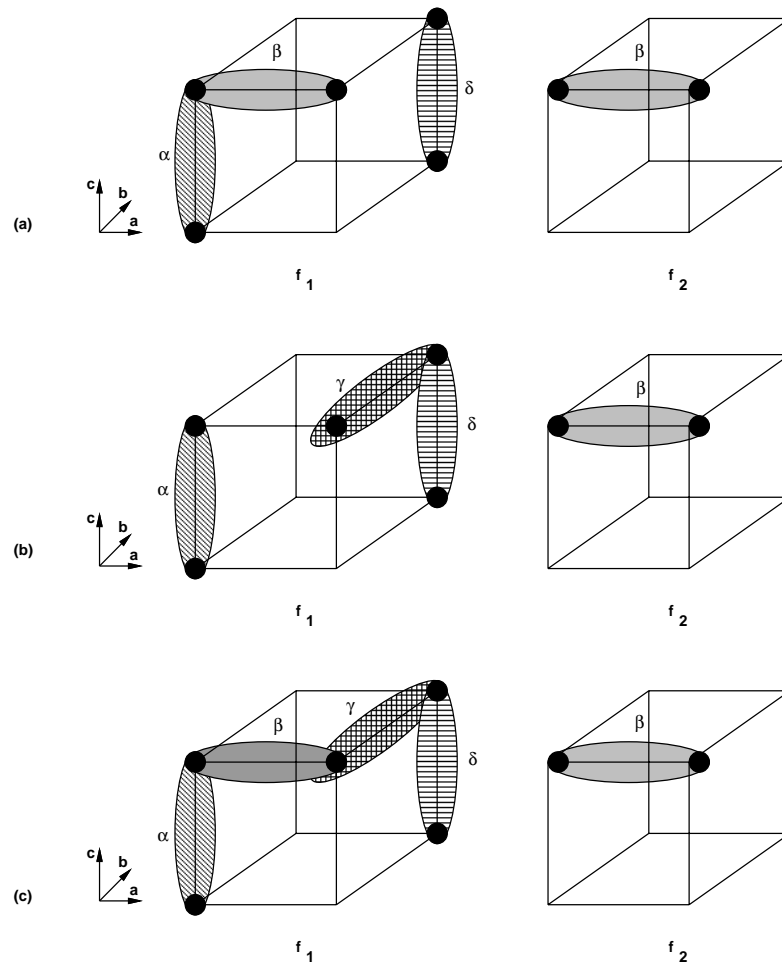
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- *Minimum cover:*
  - Cover of the function with minimum number of implicants.
  - Global optimum.
- *Minimal cover or irredundant cover:*
  - Cover of the function that is not a proper superset of another cover.
  - No implicant can be dropped.
  - Local optimum.
- *Minimal cover w.r.t. 1-implicant containment.*
  - No implicant is contained by another one.
  - Weak local optimum.

# Example

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- $f_1 = a'b'c' + a'b'c + ab'c + abc + abc'$

- $f_2 = a'b'c + ab'c$

## Definitions

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- *Prime* implicant:
  - Implicant not contained by any other implicant.
- *Prime* cover:
  - Cover of prime implicants.
- *Essential* prime implicant:
  - There exist some minterm covered only by that prime implicant.

# Logic minimization

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- *Exact* methods:
  - Compute minimum cover.
  - Often impossible for large functions.
  - Based on *Quine McCluskey* method.
- *Heuristic* methods:
  - Compute minimal covers (possibly minimum).
  - Large variety of methods and programs:
    - \* MINI, PRESTO, ESPRESSO.

## Exact logic minimization

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- *Quine's theorem:*
  - There is a minimum cover that is prime.
- Consequence:
  - Search for minimum cover can be restricted to prime implicants.
- Quine McCluskey method:
  - Compute prime implicants.
  - Determine minimum cover.

## Prime implicant table

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- Rows: minterms.
- Columns: prime implicants.
- Exponential size:
  - $2^n$  minterms.
  - Up to  $3^n/n$  prime implicants.
- Remark:
  - Some functions have much fewer primes.
  - Minterms can be grouped together.



## Example

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- Function:  $f = a'b'c' + a'b'c + ab'c + abc + abc'$

- Primes:

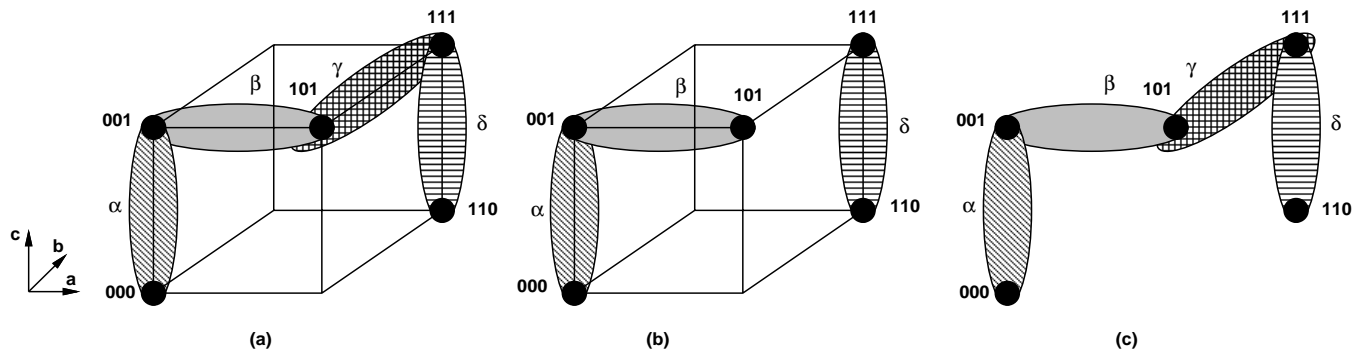
$\alpha$	00*	1
$\beta$	*01	1
$\gamma$	1*1	1
$\delta$	11*	1

- Implicant table:

	$\alpha$	$\beta$	$\gamma$	$\delta$
000	1	0	0	0
001	1	1	0	0
101	0	1	1	0
111	0	0	1	1
110	0	0	0	1

# Example

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## Minimum cover early methods

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- Reduce table:
  - Iteratively identify essentials, save them in the cover, remove covered minterms.
- *Petrick's* method.
  - Write covering clauses in *pos* form.
  - Multiply out *pos* form into *sop* form.
  - Select cube of minimum size.
  - *Remark:*
    - \* Multiplying out clauses is exponential.

## Example Petrick's method

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- *pos* clauses:

$$- (\alpha)(\alpha + \beta)(\beta + \gamma)(\gamma + \delta)(\delta) = 1$$

- *sop* form:

$$- \alpha\beta\delta + \alpha\gamma\delta = 1$$

- Solutions:

$$- \{\alpha, \beta, \delta\}$$

$$- \{\alpha, \gamma, \delta\}$$

## Matrix representation

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- View table as Boolean matrix:  $\mathbf{A}$ .
- Selection Boolean vector for primes:  $\mathbf{x}$ .
- Determine  $\mathbf{x}$  such that:
  - $\mathbf{A} \mathbf{x} \geq \mathbf{1}$ .
  - Select enough columns to cover all rows.
- Minimize cardinality of  $\mathbf{x}$ :
  - Example:  $\mathbf{x} = [1101]^T$

## Example

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$$\begin{bmatrix} 1 & 0 & 0 & 0 \\ 1 & 1 & 0 & 0 \\ 0 & 1 & 1 & 0 \\ 0 & 0 & 1 & 1 \\ 0 & 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} 1 \\ 1 \\ 0 \\ 1 \end{bmatrix} = \begin{bmatrix} 1 \\ 2 \\ 1 \\ 1 \\ 1 \end{bmatrix}$$

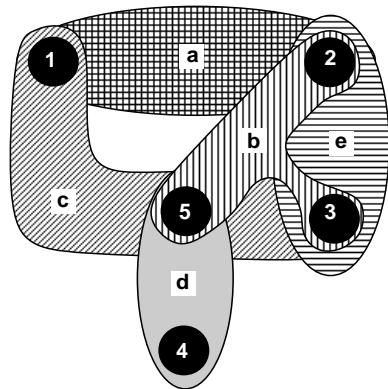
# Covering problem

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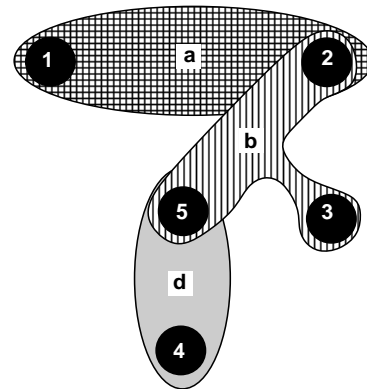
- Set covering problem:
  - A set  $S$ . (Minterm set).
  - A collection  $C$  of subsets. (Implicant set).
  - Select fewest elements of  $C$  to cover  $S$ .
- Intractable.
- Exact method:
  - Branch and bound algorithm.
- Heuristic methods.

# Example edge-cover of a hypergraph

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(a)



(b)



## Branch and bound algorithm

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- Tree search of the solution space:
  - Potentially exponential search.
- Use bounding function:
  - If the lower bound on the solution cost that can be derived from a set of future choices exceeds the cost of the best solution seen so far:
    - Kill the search.
- Good pruning may reduce run-time.

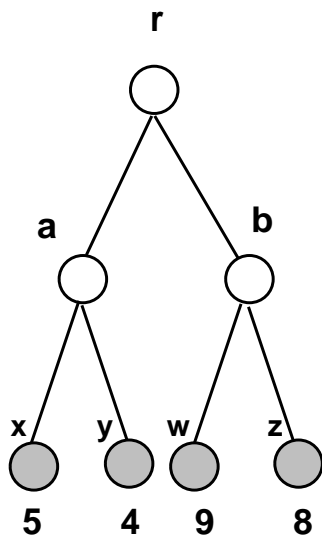
# Branch and bound algorithm

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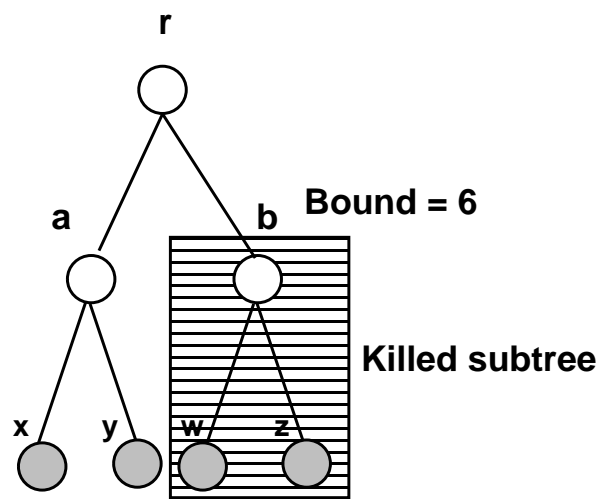
```
BRANCH_AND_BOUND {
  Current_best = anything;
  Current_cost =  $\infty$ ;
  S = s0;
  while (S  $\neq$   $\emptyset$ ) do {
    Select an element in s  $\in$  S;
    Remove s from S ;
    Make a branching decision based on s
      yielding sequences {si, i = 1, 2, ..., m};
    for ( i = 1 to m) {
      Compute the lower bound bi of si;
      if (bi  $\geq$  Current_cost)
        Kill si;
      else {
        if (si is a complete solution ) {
          Current_best = si;
          Current_cost = cost of si ;
        }
        else
          Add si to set S;
      }
    }
  }
}
```

# Example

© GDM



(a)



(b)

# Branch and bound algorithm for covering

## Reduction strategies

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- Partitioning:
  - If **A** is block diagonal:
    - \* Solve covering problem for corresponding blocks.
- Essentials (EPI):
  - Column incident to one (or more) row with single 1:
    - \* Select column.
    - \* Remove covered row(s) from table.

## Branch and bound algorithm for covering Reduction strategies

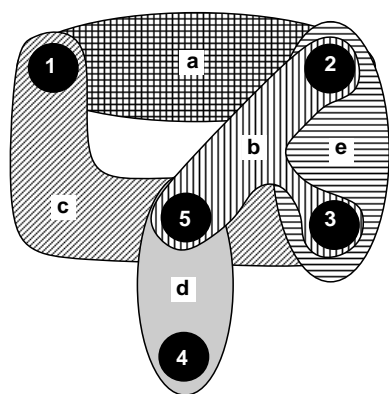
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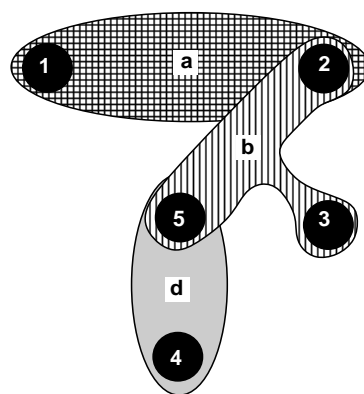
- Column (implicant) dominance:
  - If  $a_{ki} \geq a_{kj} \forall k$ :
    - \* remove column  $j$ .
  
- Row (minterm) dominance:
  - If  $a_{ik} \geq a_{jk} \forall k$  :
    - \* Remove row  $i$ .

# Example

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(a)



(b)

$$\mathbf{A} = \begin{bmatrix} 1 & 0 & 1 & 0 & 0 \\ 1 & 1 & 0 & 0 & 1 \\ 0 & 1 & 1 & 0 & 1 \\ 0 & 0 & 0 & 1 & 0 \\ 0 & 1 & 1 & 1 & 0 \end{bmatrix}$$

## Example reduction

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- Fourth column is essential.
- Fifth column is dominated.
- Fifth row is dominant.

- $\mathbf{A} = \begin{bmatrix} 1 & 0 & 1 \\ 1 & 1 & 0 \\ 0 & 1 & 1 \end{bmatrix}$

## Branch and bound covering algorithm

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```
EXACT_COVER(A, x, b) {  
    Reduce matrix A and update corresponding x;  
    if (Current_estimate  $\geq$  |b|) return(b);  
    if (A has no rows ) return (x);  
    Select a branching column c;  
     $x_c = 1$  ;  
     $\tilde{\mathbf{A}} = \mathbf{A}$  after deleting c and rows incident to it;  
     $\tilde{\mathbf{x}} = \text{EXACT\_COVER}(\tilde{\mathbf{A}}, \mathbf{x}, \mathbf{b})$ ;  
    if ( | $\tilde{\mathbf{x}}$ | < |b|)  
        b =  $\tilde{\mathbf{x}}$  ;  
     $x_c = 0$  ;  
     $\tilde{\mathbf{A}} = \mathbf{A}$  after deleting c ;  
     $\tilde{\mathbf{x}} = \text{EXACT\_COVER}(\tilde{\mathbf{A}}, \mathbf{x}, \mathbf{b})$ ;  
    if ( | $\tilde{\mathbf{x}}$ | < |b|)  
        b =  $\tilde{\mathbf{x}}$  ;  
    return (b);  
}
```



## Bounding function

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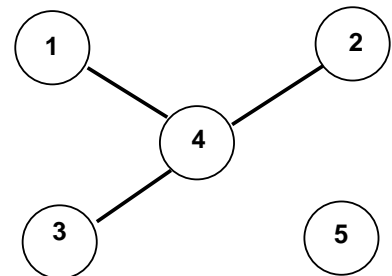
- Estimate lower bound on the covers derived from the current  $\mathbf{x}$ .
- The sum of the ones in  $\mathbf{x}$ , plus bound on cover for local  $\mathbf{A}$ :
  - Independent set of rows:
    - \* No 1 in same column.
  - Build graph denoting pairwise independence.
  - Find clique number.
  - Approximation (lower) is acceptable.

## Example

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$$\mathbf{A} = \begin{bmatrix} 1 & 0 & 1 & 0 & 0 \\ 1 & 1 & 0 & 0 & 1 \\ 0 & 1 & 1 & 0 & 1 \\ 0 & 0 & 0 & 1 & 0 \\ 0 & 1 & 1 & 1 & 0 \end{bmatrix}$$

- Row 4 independent from 1,2,3.
- Clique number is 2.



- Bound is 2.

## Example

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- $\mathbf{A} = \begin{bmatrix} 1 & 0 & 1 \\ 1 & 1 & 0 \\ 0 & 1 & 1 \end{bmatrix}$

- There are no independent rows.
- Clique number is 1 (one vertex).
- Bound is  $1 + 1$  (already selected essential).

## Example

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- $\mathbf{A} = \begin{bmatrix} 1 & 0 & 1 \\ 1 & 1 & 0 \\ 0 & 1 & 1 \end{bmatrix}$

- Choose first column:
  - Recur with  $\widetilde{\mathbf{A}} = [11]$ .
    - \* Delete one dominated column.
    - \* Take other column (essential).
  - New cost is 3.
- Exclude first column:
  - Find another solution with cost 3 (discarded).

# ESPRESSO-EXACT

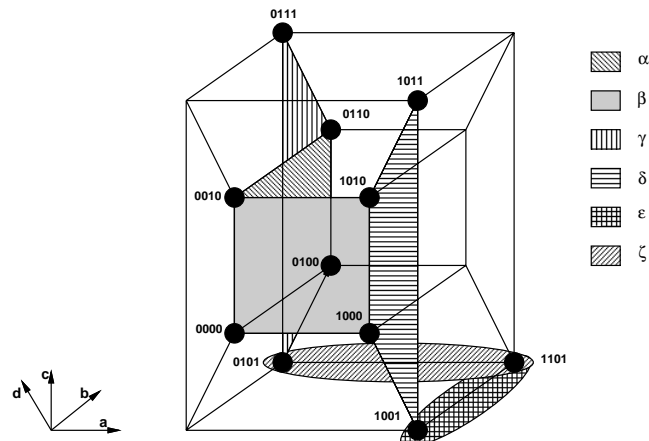
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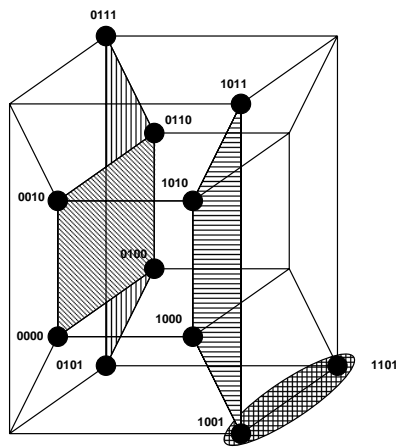
- Exact minimizer [Rudell].
- Exact *branch and bound* covering.
- Compact implicant table:
  - Group together minterms covered by the same implicants.
- Very efficient. Solves most problems.

# Example

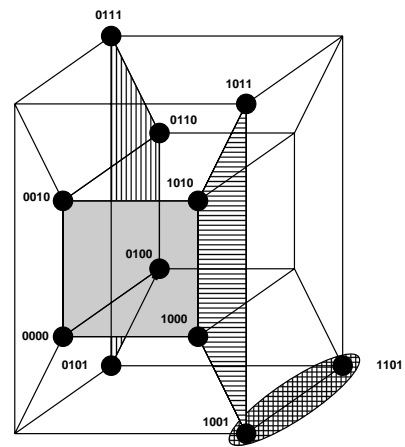
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(a)



(b)



(c)

$\alpha$	$0**0$	1
$\beta$	$*0*0$	1
$\gamma$	$01**$	1
$\delta$	$10**$	1
$\epsilon$	$1*01$	1
$\zeta$	$*101$	1

**Example**  
**Prime implicant table**  
**(after removing essentials)**

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	$\alpha$	$\beta$	$\epsilon$	$\zeta$
0000,0010	1	1	0	0
1101	0	0	1	1

## Recent developments

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- Many minimization problems can be solved exactly today.
- Usually bottleneck is table size.
- Implicit representation of prime implicants:
  - Methods based on BDDs [COUDERT]:
    - \* To represent sets.
    - \* To do dominance simplification.
  - Methods based on signature cubes [MCGEER]
    - \* Represent set of primes.



# Summary

## Exact two-level minimization of logic functions

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- Based on derivatives of Quine-McCluskey method.
- Many minimization problems can be now solved exactly.
- Usual problems are memory size and time.

# Boolean relations

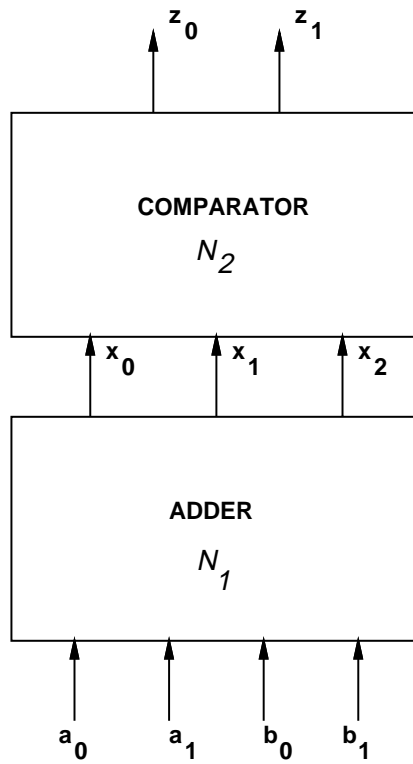
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- Generalization of Boolean functions.
- More than one output pattern may correspond to an input pattern.
- Some *degrees of freedom* in finding an implementation:
  - More general than *don't care* conditions.
- Problem:
  - Given a Boolean relation, find minimum cover of a compatible function.

# Example

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- Compare:

- $\mathbf{a + b > 4 ?}$

- $\mathbf{a + b < 3 ?}$

## Example

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$a_1$	$a_0$	$b_1$	$b_0$	$x$
0	0	0	0	{ 000, 001, 010 }
0	0	0	1	{ 000, 001, 010 }
0	0	1	0	{ 000, 001, 010 }
0	1	0	0	{ 000, 001, 010 }
1	0	0	0	{ 000, 001, 010 }
0	1	0	1	{ 000, 001, 010 }
0	0	1	1	{ 011, 100 }
0	1	1	0	{ 011, 100 }
1	0	0	1	{ 011, 100 }
1	0	1	0	{ 011, 100 }
1	1	0	0	{ 011, 100 }
0	1	1	1	{ 011, 100 }
1	1	0	1	{ 011, 100 }
1	0	1	1	{ 101, 110, 111 }
1	1	1	0	{ 101, 110, 111 }
1	1	1	1	{ 101, 110, 111 }

## Example (2)

### Minimum implementation

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$a_1$	$a_0$	$b_1$	$b_0$	$x$
0	*	1	*	010
1	*	0	*	010
1	*	1	*	100
*	*	*	1	001
*	1	*	*	001

- Remark:
  - Circuit is no longer an adder.

## Minimization of Boolean relations

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- Since there are many possible output values there are many logic functions implementing the relation.
  - Compatible functions.
- Find a function with minimum cardinality.
- Do not enumerate all possible functions:
  - May be too many.
- Represent the primes of all possible functions:
  - Compatible primes (*c – primes*).

## Minimization of Boolean relation

---

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- Exact:
  - Find a set of compatible primes.
  - Solve a *binate* covering problem.
    - \* Consistency relations.
- Heuristic:
  - Iterative improvement [GYOCRO].

## Example

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- Boolean relation:

0	0	0		{ 00 }
0	0	1		{ 00 }
0	1	0		{ 00 }
0	1	1		{ 10 }
1	0	0		{ 00 }
1	0	1		{ 01 }
1	1	0		{ 00, 11 }
1	1	1		{ 00, 11 }

- Compatible primes:

$\alpha$		0	1	1		10
$\beta$		1	0	1		01
$\gamma$		1	1	0		11
$\delta$		1	1	1		11
$\epsilon$		*	1	1		10
$\zeta$		1	*	1		01
$\eta$		1	1	*		11



## Example

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- Input 011 – output 10.
  - Covering clause  $(\alpha + \epsilon)$ .
- Input 111 – output 00 or 11.
  - No implicant – 00 – correct.
  - Either  $\eta$  or  $\epsilon \cup \zeta$  – output 11 – correct.
  - Only  $\epsilon$  or  $\zeta$  is selected – output 10 or 01 – WRONG.
  - Covering clause  $\eta + \epsilon\zeta + \epsilon'\zeta'$  – binate.
- Overall covering clause:  
$$(\alpha + \epsilon) \cdot (\beta + \zeta) \cdot (\epsilon + \zeta' + \eta) \cdot (\epsilon' + \zeta + \eta)$$

## Binate covering

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- Covering problem with *binate clause*.
- Implications:
  - The selection of a prime may exclude other primes.
- No guarantee of finding a feasible solution:
  - Inconsistent clauses.
- *Minimum-cost satisfiability* problem.
  - Much harder to solve than unate cover.
  - Branch and bound algorithm.
  - BDD-based methods.

# Summary

## Boolean relations

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- Generalization of Boolean functions.
  - Many possible output patterns.
- Useful for modeling:
  - Cascaded blocks.
  - Portions of multiple-level networks.
- More degree of freedom in implementation.
- Harder problem to solve.