

# ALGEBRAIC METHODS

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# Outline

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- Algebraic model.
- Division and substitution.
- Kernel theory.
  - Kernel and cube extraction.
- Decomposition.

## Algebraic model

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- Boolean algebra:
  - Complement.
  - Symmetric distribution laws.
  - *Don't care* sets.
- Algebraic methods:
  - Boolean functions  $\rightarrow$  polynomials.
  - Expressions (*sum of product* forms).

## Algebraic division

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- Given two algebraic expressions:
- $f_{\text{quotient}} = f_{\text{dividend}} / f_{\text{divisor}}$  when:
  - $f_{\text{dividend}} = f_{\text{divisor}} \cdot f_{\text{quotient}} + f_{\text{remainder}}$
  - $f_{\text{divisor}} \cdot f_{\text{quotient}} \neq 0$
  - and the support of  $f_{\text{divisor}}$  and  $f_{\text{quotient}}$  is disjoint.

## Example

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- Algebraic division:
  - Let  $f_{dividend} = ac + ad + bc + bd + e$   
and  $f_{divisor} = a + b$
  - Then  $f_{quotient} = c + d$      $f_{remainder} = e$
  - Because  $(a + b) \cdot (c + d) + e = f_{dividend}$   
and  $\{a, b\} \cap \{c, d\} = \emptyset$ .
- Non-algebraic division:
  - Let  $f_i = a + bc$  and  $f_j = a + b$ .
  - Then  $(a + b) \cdot (a + c) = f_i$   
but  $\{a, b\} \cap \{a, c\} \neq \emptyset$ .

## An algorithm for division

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- $A = \{C_j^A, j = 1, 2, \dots, l\}$  set of cubes (monomials) of the dividend.
- $B = \{C_i^B, i = 1, 2, \dots, n\}$  set of cubes (monomials) of the divisor.
- Quotient  $Q$  and remainder  $R$  are sum of cubes (monomials).

## An algorithm for division

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```
ALGEBRAIC_DIVISION(A, B) {
  for (i = 1 to n) {
    D = {CjA such that CjA ⊇ CiB};
    if ( D == ∅ ) return(∅, A);
    Di = D with var. in sup(CiB) dropped ;
    if i = 1
      Q = Di;
    else
      Q = Q ∩ Di;
  }
  R = A - Q × B;
  return(Q, R);
}
```

## Example

$$f_{dividend} = ac + ad + bc + bd + e;$$

$$f_{divisor} = a + b;$$

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- $A = \{ac, ad, bc, bd, e\}$  and  $B = \{a, b\}$ .
- $i = 1$ :
  - $C_1^B = a$ ,  $D = \{ac, ad\}$  and  $D_1 = \{c, d\}$ .
  - Then  $Q = \{c, d\}$ .
- $i = 2 = n$ :
  - $C_2^B = b$ ,  $D = \{bc, bd\}$  and  $D_2 = \{c, d\}$ .
  - Then  $Q = \{c, d\} \cap \{c, d\} = \{c, d\}$ .
- Result:
  - $Q = \{c, d\}$  and  $R = \{e\}$ .
  - $f_{quotient} = c + d$  and  $f_{remainder} = e$ .



## Theorem

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- Given  $f_i$  and  $f_j$ , then  $f_i/f_j$  is empty when:
  - $f_j$  contains a variable not in  $f_i$ .
  - $f_j$  contains a cube whose support is not contained in that of any cube of  $f_i$ .
  - $f_j$  contains more terms than  $f_i$ .
  - The count of any variable in  $f_j$  than in  $f_i$ .

# Substitution

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- Consider expression pairs.
- Apply division (in any order).
- If quotient is not void:
  - Evaluate area/delay gain
  - Substitute  $f_{dividend}$  by  $j \cdot f_{quotient} + f_{remainder}$   
where  $j = f_{divisor}$ .
- Use filters to reduce divisions.

## Substitution algorithm

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```
SUBSTITUTE(  $G_n(V, E)$  ){
  for ( $i = 1, 2, \dots, |V|$ ) {
    for ( $j = 1, 2, \dots, |V|; j \neq i$ ) {
       $A =$  set of cubes of  $f_i$ ;
       $B =$  set of cubes of  $f_j$ ;
      if ( $A, B$  pass the filter test ) {
        ( $Q, R$ ) = ALGEBRAIC_DIVISION( $A, B$ )
        if ( $Q \neq \emptyset$ ) {
           $f_{quotient} =$  sum of cubes of  $Q$ ;
           $f_{remainder} =$  sum of cubes of  $R$ ;
          if ( substitution is favorable)
             $f_i = j \cdot f_{quotient} + f_{remainder}$ ;
        }
      }
    }
  }
}
```

# Extraction

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- Search for common sub-expressions:
  - Single-cube extraction: monomial.
  - Multiple-cube (kernel) extraction.
- Search for appropriate divisors.

## Definitions

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- *Cube-free* expression:
  - Cannot be factored by a cube.
- *Kernel* of an expression:
  - Cube-free quotient of the expression divided by a cube, called *co-kernel*.
- *Kernel set*  $K(f)$  of an expression:
  - Set of kernels.

## Example

$$f_x = ace + bce + de + g$$

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- Divide  $f_x$  by  $a$ . Get  $ce$ . Not cube free.
- Divide  $f_x$  by  $b$ . Get  $ce$ . Not cube free.
- Divide  $f_x$  by  $c$ . Get  $ae + be$ . Not cube free.
- Divide  $f_x$  by  $ce$ . Get  $a + b$ . Cube free. **Kernel!**
- Divide  $f_x$  by  $d$ . Get  $e$ . Not cube free.
- Divide  $f_x$  by  $e$ . Get  $ac + bc + d$ . Cube free. **Kernel!**
- Divide  $f_x$  by  $g$ . Get 1. Not cube free.
- Expression  $f_x$  is a kernel of itself because cube free.
- $K(f_x) = \{(a + b); (ac + bc + d); (ace + bce + de + g)\}$ .

## Theorem (Brayton and McMullen)

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- Two expressions  $f_a$  and  $f_b$  have a common multiple-cube divisor  $f_d$  if and only if:
  - there exist kernels  $k_a \in K(f_a)$  and  $k_b \in K(f_b)$  s.t.  $f_d$  is the sum of 2 (or more) cubes in  $k_a \cap k_b$ .
- Consequence:
  - If kernel intersection is void, then the search for common sub-expression can be dropped.

## Example

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$$\begin{aligned}f_x &= ace + bce + de + g \\f_y &= ad + bd + cde + ge \\f_z &= abc\end{aligned}$$

- $K(f_x) = \{(a + b); (ac + bc + d); (ace + bce + de + g)\}$ .
- $K(f_y) = \{(a + b + ce); (cd + g); (ad + bd + cde + ge)\}$ .
- The kernel set of  $f_z$  is empty.
- Select intersection  $(a + b)$

$$\begin{aligned}f_w &= a + b \\f_x &= wce + de + g \\f_y &= wd + cde + ge \\f_z &= abc\end{aligned}$$



## Kernel set computation

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- Naive method:
  - Divide function by elements in power set of its support set.
  - Weed out non cube-free quotients.
- Smart way:
  - Use recursion:
    - \* Kernels of kernels are kernels.
  - Exploit commutativity of multiplication.

## Recursive kernel computation simple algorithm

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```
R_KERNELS(f){
  K = ∅;
  foreach variable x ∈ sup(f) {
    if(|CUBES(f, x)| ≥ 2) {
      fC = largest cube containing x,
      s.t. CUBES(f, C) = CUBES(f, x);
      K = K ∪ R_KERNELS(f/fC);
    }
  }
  K = K ∪ f;
  return(K);
}

CUBES(f, C){
  return the cubes of f whose support ⊇ C;
}
```

# Analysis

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- Some computation may be redundant:
  - Example:
    - \* Divide by  $a$  and then by  $b$ .
    - \* Divide by  $b$  and then by  $a$ .
  - Obtain duplicate kernels.
- Improvement:
  - Keep a *pointer* to literals used so far.

## Recursive kernel computation

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```
KERNELS(f, j) {
  K = ∅;
  for i = j to n {
    if(|CUBES(f, xi)| ≥ 2) {
      fC = largest cube containing x,
      s.t. CUBES(f, C) = CUBES(f, xi);
      if (xk ∉ C ∀ k < i)
        K = K ∪ KERNELS(f/fC, i + 1);
    }
  }
  K = K ∪ f;
  return(K);
}
```

## Example

$$f = ace + bce + de + g$$

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- Literals  $a$  or  $b$ . No action required.
- Literal  $c$ . Select cube  $ce$ :
  - Recursive call with arguments:  $(ace + bce)/ce = a + b$ ; pointer  $j = 3 + 1$ .
  - Call considers variables  $\{d, e, g\}$ . No kernel.
  - Adds  $a + b$  to the kernel set at the last step.
- Literal  $d$ . No action required.
- Literal  $e$ . Select cube  $e$ :
  - Recursive call with arguments:  $ac + bc + d$  and pointer  $j = 5 + 1$ .
  - Call considers variable  $\{g\}$ . No kernel.
  - Adds  $ac + bc + d$  to the kernel set at the last step.
- Literal  $g$ . No action required.
- Adds  $ace + bce + de + g$  to the kernel set.
- $K = \{(ace + bce + de + g), (ac + bc + d), (a + b)\}$ .

## Matrix representation of kernels

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- Boolean matrix:
  - Rows: cubes. Columns: variables.
- Rectangle  $(R, C)$ :
  - Subset of rows and columns with all entries equal to 1.
- Prime rectangle:
  - Rectangle not inside any other rectangle.
- Co-rectangle  $(R, C')$  of a rectangle  $(R, C)$ :
  - $C'$  are the columns not in  $C$ .
- A co-kernel corresponds to a prime rectangle with at least two rows.

## Example

$$f_x = ace + bce + de + g$$

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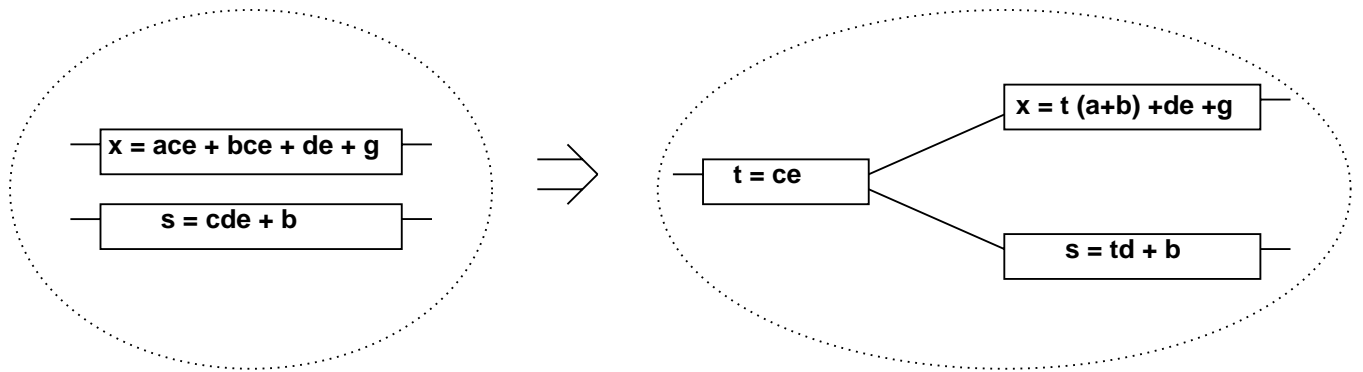
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	var	<i>a</i>	<i>b</i>	<i>c</i>	<i>d</i>	<i>e</i>	<i>g</i>
cube	$R \setminus C$	1	2	3	4	5	6
<i>ace</i>	1	1	0	1	0	1	0
<i>bce</i>	2	0	1	1	0	1	0
<i>de</i>	3	0	0	0	1	1	0
<i>g</i>	4	0	0	0	0	0	1

- Rectangle (prime):  $(\{1, 2\}, \{3, 5\})$ 
  - Co-kernel  $ce$ .
- Co-rectangle:  $(\{1, 2\}, \{1, 2, 4, 6\})$ .
  - Kernel  $a + b$ .

# Single-cube extraction

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## Single-cube extraction

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- Form *auxiliary* function:
  - Sum of all local functions.
- Form matrix representation:
  - A rectangle with two rows represents a *common cube*.
  - Best choice is a prime rectangle.
- Use function ID for cubes:
  - Cube intersection from different functions.

## Example

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- Expressions:

- $f_x = ace + bce + de + g$

- $f_s = cde + b$

- Auxiliary function:

- $f_{aux} = ace + bce + de + g + cde + b$

- Matrix:

		var	<i>a</i>	<i>b</i>	<i>c</i>	<i>d</i>	<i>e</i>	<i>g</i>
cube	ID	$R \setminus C$	1	2	3	4	5	6
<i>ace</i>	x	1	1	0	1	0	1	0
<i>bce</i>	x	2	0	1	1	0	1	0
<i>de</i>	x	3	0	0	0	1	1	0
<i>g</i>	x	4	0	0	0	0	0	1
<i>cde</i>	s	5	0	0	1	1	1	0
<i>b</i>	s	6	0	1	0	0	0	0

- Prime rectangle:  $(\{1, 2, 5\}, \{3, 5\})$
- Extract cube *ce*.

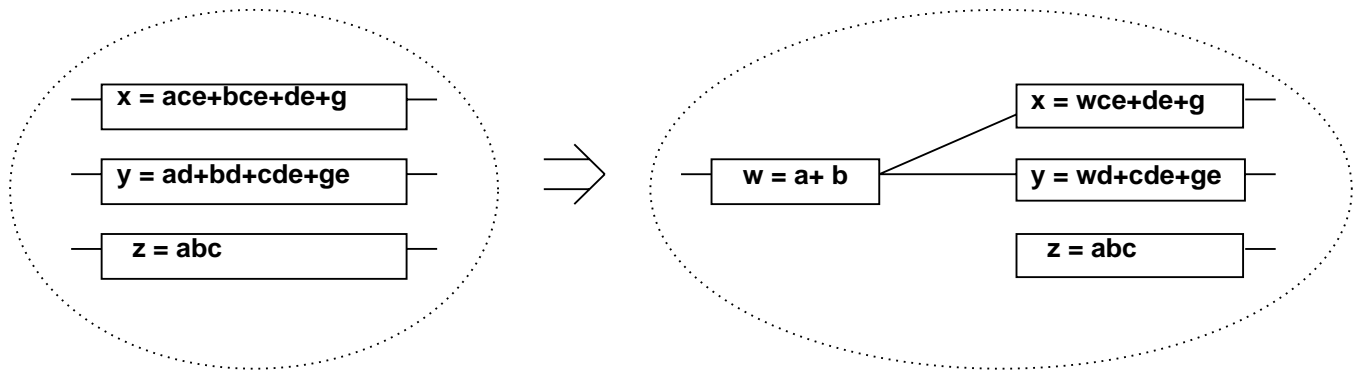
## Cube extraction algorithm

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```
CUBE_EXTRACT(  $G_n(V, E)$  ) {  
  while (some favorable common cube exist) {  
     $C$  = select common cube to extract;  
    Generate new label  $l$ ;  
    Add to network  $v_l$  and  $f_l = f^C$ ;  
    Replace all functions  $f$ , where  $f_l$  is a divisor,  
      by  $l \cdot f_{quotient} + f_{remainder}$ ;  
  }  
}
```

## Multiple-cube extraction

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## Multiple-cube extraction

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- We need a kernel/cube matrix.
- Relabeling:
  - Cubes by new variables.
  - Kernels by cubes.
- Form *auxiliary* function:
  - Sum of all kernels.
- Extend cube intersection algorithm.

## Example

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- $f_p = ace + bce.$ 
  - $K(f_p) = \{(a + b)\}.$
- $f_q = ae + be + d.$ 
  - $K(f_q) = \{(a + b); (ae + be + d)\}.$
- Relabeling:
  - $x_a = a; x_b = b; x_{ae} = ae; x_{be} = be; x_d = d;$
  - \*  $K(f_p) = \{\{x_a, x_b\}\}$
  - \*  $K(f_q) = \{\{x_a, x_b\}; \{x_{ae}, x_{be}, x_d\}\}.$

## Example (2)

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- $f_{aux} = x_a x_b + x_a x_b + x_a e x_b e x_d$ .
- Co-kernel:  $x_a x_b$ .
  - $x_a x_b$  corresponds to kernel intersection  $a + b$ .
  - Extract  $a + b$  from  $f_p$  and  $f_q$ .

## Kernel extraction algorithm

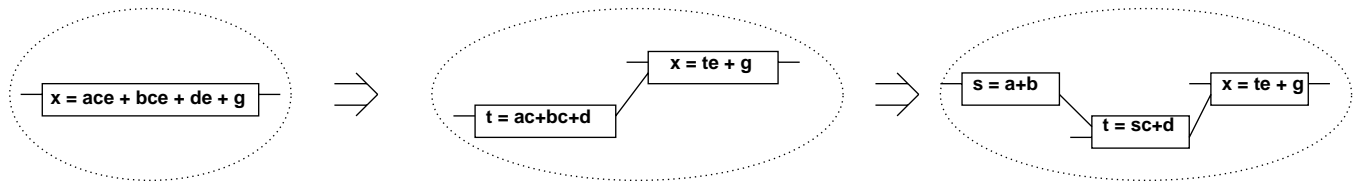
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```
KERNEL_EXTRACT(  $G_n(V, E)$  ,  $n, k$ ){  
  while (some favorable common kernel intersection exist)  
    Compute kernel set of level  $\leq k$ ;  
    for ( $i = 1$  to  $n$ ) {  
      Compute kernel intersections;  
       $f =$  select kernel intersection to extract;  
      Generate new label  $l$ ;  
      Add  $v_l$  to the network with expression  $f_l = f$ ;  
      Replace all functions  $f$  where  $f_l$  is a divisor  
        by  $l \cdot f_{quotient} + f_{remainder}$ ;  
    }  
  }  
}
```



# Decomposition

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# Decomposition

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- Different ways:
  - Method of Ashenhurst and Curtis.
  - NAND/NOR decomposition.
- Kernel-based decomposition:
  - Divide expression recursively.

## Example

$$f_x = ace + bce + de + g$$

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- Select kernel  $ac + bc + d$ .
- Decompose:  $f_x = te + g$ ;  $f_t = ac + bc + d$ ;
- Recur on the quotient  $f_t$ :
  - Select kernel  $a + b$ :
  - Decompose:  $f_t = sc + d$ ;  $f_s = a + b$ ;

## Decomposition algorithm

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```
DECOMPOSE(  $G_n(V, E)$  ,  $k$  ){  
  repeat {  
     $v_x$  = selected vertex with expression  
      whose size is above  $k$ ;  
    if ( $v_x = \emptyset$ ) return;  
    decompose expression  $f_x$ ;  
  }  
}
```

# Summary

## Algebraic transformations

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- View Boolean functions as algebraic expression.
- Fast manipulation algorithms.
- Some optimality lost, because Boolean properties are neglected.
- Useful to reduce large networks.